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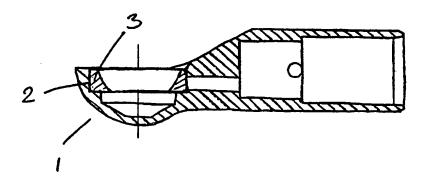
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(57) Abstract

Device for fixing a bearing means firmly in a three-axle ball and socket joint arranged in a robot. The bearing means is arranged in a housing (2) on the joint socket (1) and the housing (2) includes surface (4) against which the bearing means abuts. Surface (4) is designed with friction-increasing means (5) that grip the bearing means and hold it.